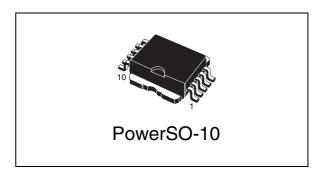


## Single channel high-side solid-state relay

#### **Features**

Туре	R <sub>DS(on)</sub>	l <sub>out</sub>	V <sub>CC</sub>
VN920SP	15 m $\Omega$	30 A	36 V

- CMOS compatible input
- Proportional load current sense
- Shorted load protection
- Under-voltage and over-voltage shutdown
- Over-voltage clamp
- Thermal shutdown
- Current limitation
- Protection against loss of ground and loss of V<sub>CC</sub>
- Very low standby power dissipation
- Reverse battery protected (see Application schematic)



### **Description**

The VN920SP is a monolithic device designed in STMicroelectronics VIPower M0-3 technology. The VN920SP is intended for driving any type of load with one side connected to ground. The active  $V_{CC}$  pin voltage clamp protects the device against low energy spikes (see ISO7637 transient compatibility table). Active current limitation combined with thermal shutdown and automatic restart protects the device against over-load.

The device integrates an analog current sense output which delivers a current proportional to the load current. The device automatically turns off in the case where the ground pin becomes disconnected.

Table 1. Device summary

Pankaga	Order	codes	
Package	Tube	Tape and reel	
PowerSO-10	VN920SP VN920SP13TR		

Contents VN920SP

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### 1 Block diagram and pin description

Figure 1. Block diagram

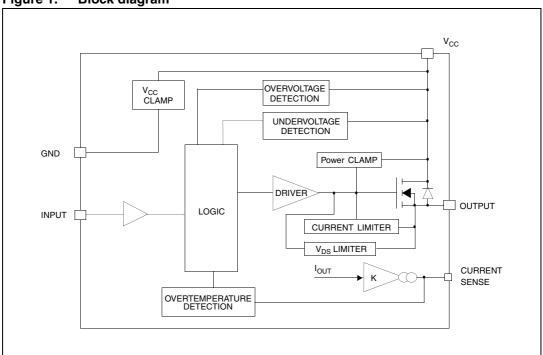


Figure 2. Configuration diagram (top view)

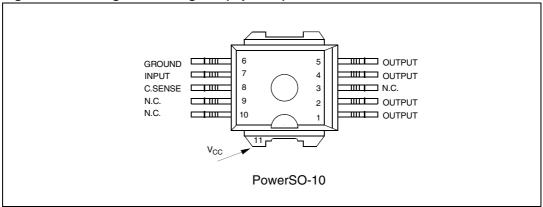
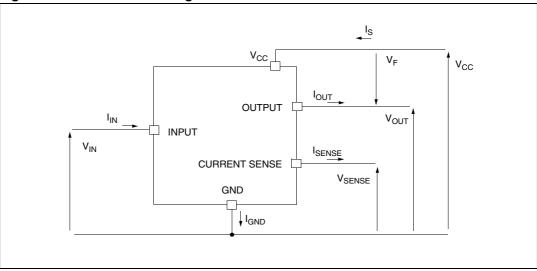


Table 2. Suggested connections for unused and not connected pins

Connection / pin	Current Sense	N.C.	Output	Input
Floating		Х	Х	X
To ground	Through 1KΩ resistor	х		Through 10KΩ resistor

### 2 Electrical specifications

Figure 3. Current and voltage conventions



### 2.1 Absolute maximum ratings

Stressing the device above the rating listed in the "Absolute maximum ratings" table may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to Absolute maximum rating conditions for extended periods may affect device reliability. Refer also to the STMicroelectronics sure program and other relevant quality document.

Table 3. Absolute maximum ratings

Symbol	Parameter	Value	Unit
V <sub>CC</sub>	DC supply voltage	41	V
- V <sub>CC</sub>	Reverse DC supply voltage	- 0.3	V
- I <sub>gnd</sub>	DC reverse ground pin current	- 200	mA
I <sub>OUT</sub>	DC output current	Internally limited	Α
- I <sub>OUT</sub>	Reverse DC output current	- 40	Α
I <sub>IN</sub>	DC input current	+/- 10	mA
V <sub>CSENSE</sub>	Current Sense maximum voltage	- 3 + 15	V V
V <sub>ESD</sub>	Electrostatic discharge (human body model: $R = 1.5 \text{K}\Omega$ ; $C = 100 \text{pF}$ ) INPUT CURRENT SENSE OUTPUT $V_{\text{CC}}$	4000 2000 5000 5000	V V V

Table 3. Absolute maximum ratings (continued)

Symbol	Parameter	Value	Unit
E <sub>MAX</sub>	Maximum switching energy (L = 0.25mH; R <sub>L</sub> = 0 $\Omega$ ; V <sub>bat</sub> = 13.5V; T <sub>jstart</sub> = 150 $^{\circ}$ C; I <sub>L</sub> = 45A)	362	mJ
P <sub>tot</sub>	Power dissipation T <sub>C</sub> ≤25°C	96.1	W
Tj	Junction operating temperature	Internally limited	°C
T <sub>c</sub>	Case operating temperature	- 40 to 150	°C
T <sub>stg</sub>	Storage temperature	- 55 to 150	°C

### 2.2 Thermal data

Table 4. Thermal data

Symbol	Parameter	Max. v	Unit	
R <sub>thj-case</sub>	Thermal resistance junction-case	ermal resistance junction-case 1.3		°C/W
<b>D</b>	Thermalregistance junction-ambient	51.3 <sup>(1)</sup>	37 <sup>(2)</sup>	°C/W
R <sub>thj-amb</sub> Thermalresistance junction-ambient		31.3	31.7	°C/W

<sup>1.</sup> When mounted on FR4 printed circuit board with 0.5cm<sup>2</sup> of Cu (at least 35µm thick).

<sup>2.</sup> When mounted on FR4 printed circuit board with  $6\text{cm}^2$  of Cu (at least  $35\mu\text{m}$  thick).

### 2.3 Electrical characteristics

Values specified in this section are for  $8V < V_{CC} < 36V$ ;  $-40^{\circ}C < T_j < 150^{\circ}C$ , unless otherwise stated.

Table 5. Power

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
V <sub>CC</sub>	Operating supply voltage		5.5	13	36	V
V <sub>USD</sub>	Under-voltage shutdown		3	4	5.5	V
V <sub>OV</sub>	Over-voltage shutdown		36			٧
R <sub>ON</sub>	On-state resistance	$I_{OUT} = 10A; T_j = 25^{\circ}C;$ $I_{OUT} = 10A;$ $I_{OUT} = 3A; V_{CC} = 6V$			15 30 50	$m\Omega$ $m\Omega$
V <sub>CLAMP</sub>	Clamp voltage	I <sub>CC</sub> = 20mA	41	48	55	V
I <sub>S</sub>	Supply current	Off-state; $V_{CC} = 13V$ ; $V_{IN} = V_{OUT} = 0V$ Off-state; $V_{CC} = 13V$ ; $V_{IN} = V_{OUT} = 0V$ ; $T_j = 25^{\circ}C$		10	25 20	μΑ
		On-state; $V_{CC} = 13V$ ; $V_{IN} = 5V$ ; $I_{OUT} = 0A$ ; $R_{SENSE} = 3.9 \text{ k}\Omega$			5	mA
I <sub>L(off1)</sub>	Off-state output current	$V_{IN} = V_{OUT} = 0V$	0		50	μΑ
I <sub>L(off2)</sub>	Off-state output current	V <sub>IN</sub> = 0V; V <sub>OUT</sub> = 3.5V	-75		0	μΑ
I <sub>L(off3)</sub>	Off-state output current	$V_{IN} = V_{OUT} = 0V; V_{CC} = 13V;$ $T_j = 125$ °C			5	μΑ
I <sub>L(off4)</sub>	Off-state output current	$V_{IN} = V_{OUT} = 0V; V_{CC} = 13V;$ $T_j = 25^{\circ}C$			3	μΑ

Note:  $V_{CLAMP}$  and  $V_{OV}$  are correlated. Typical difference is 5V.

Table 6. Switching (V<sub>CC</sub>=13V)

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
t <sub>d(on)</sub>	Turn-on delay time	$R_L = 1.3\Omega$ (see <i>Figure 4.</i> )		50		μs
t <sub>d(off)</sub>	Turn-off delay time	$R_L = 1.3\Omega$ (see <i>Figure 4.</i> )		50		μs
dV <sub>OUT</sub> /dt <sub>(on)</sub>	Turn-on voltage slope	$R_L = 1.3\Omega$ (see <i>Figure 4.</i> )	See Figure 10.		10.	V/µs
dV <sub>OUT</sub> /dt <sub>(off)</sub>	Turn-off voltage slope	$R_L = 1.3\Omega$ (see <i>Figure 4.</i> )	See Figure 12.		12.	V/µs

Table 7. Logic inputs

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
V <sub>IL</sub>	Input low-level voltage				1.25	V
I <sub>IL</sub>	Low-level input current	V <sub>IN</sub> = 1.25V	1			μΑ
V <sub>IH</sub>	Input high-level voltage		3.25			V
I <sub>IH</sub>	High-level input current	V <sub>IN</sub> = 3.25V			10	μΑ
V <sub>I(hyst)</sub>	Input hysteresis voltage		0.5			V
V <sub>ICL</sub>	Input clamp voltage	I <sub>IN</sub> = 1mA I <sub>IN</sub> = - 1mA	6	6.8 - 0.7	8	V V

Table 8. Current sense (9V ≤V<sub>CC</sub> ≤16V)

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
К <sub>1</sub>	I <sub>OUT</sub> /I <sub>SENSE</sub>	$I_{OUT} = 1A; V_{SENSE} = 0.5V;$ $T_j = -40^{\circ}C150^{\circ}C$	3300	4400	6000	
dK <sub>1</sub> /K <sub>1</sub>	Current sense ratio drift	$I_{OUT} = 1A; V_{SENSE} = 0.5V;$ $T_j = -40^{\circ}C150^{\circ}C$	-10		+10	%
K <sub>2</sub>	I <sub>OUT</sub> /I <sub>SENSE</sub>	$I_{OUT} = 10A; V_{SENSE} = 4V;$ $T_{j} = -40^{\circ}C$ $T_{j} = 25^{\circ}C150^{\circ}C$	4200 4400	4900 4900	6000 5750	
dK <sub>2</sub> /K <sub>2</sub>	Current sense ratio drift	$I_{OUT} = 10A; V_{SENSE} = 4V;$ $T_j = -40^{\circ}C150^{\circ}C$	-8		+8	%
К <sub>3</sub>	I <sub>OUT</sub> /I <sub>SENSE</sub>	$I_{OUT} = 30A; V_{SENSE} = 4V;$ $T_{j} = -40^{\circ}C$ $T_{j} = 25^{\circ}C150^{\circ}C$	4200 4400	4900 4900	5500 5250	
dK <sub>3</sub> /K <sub>3</sub>	Current sense ratio drift	$I_{OUT} = 30A; V_{SENSE} = 4V;$ $T_j = -40^{\circ}C150^{\circ}C$	-6		+6	%
I <sub>SENSE0</sub>	Analog sense current	$V_{CC} = 616V; I_{OUT} = 0A;$ $V_{SENSE} = 0V;$ $T_j = -40^{\circ}C150^{\circ}C$	0		10	μΑ
V <sub>SENSE</sub>	Max analog sense output voltage	$V_{CC}$ = 5.5V; $I_{OUT}$ = 5A; $R_{SENSE}$ = 10k $\Omega$ $V_{CC}$ > 8V, $I_{OUT}$ = 10A; $R_{SENSE}$ = 10k $\Omega$	2			V V
V <sub>SENSEH</sub>	Sense voltage in over-temperature condition	$V_{CC} = 13V; R_{SENSE} = 3.9k\Omega$		5.5		V

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Table 8. Current sense (9V ≤V<sub>CC</sub> ≤16V) (continued)

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
R <sub>VSENSEH</sub>	Analog sense output impedance in over-temperature condition	V <sub>CC</sub> = 13V; T <sub>j</sub> > T <sub>TSD</sub> ; output open		400		Ω
t <sub>DSENSE</sub>	Current sense delay response	To 90% I <sub>SENSE</sub> <sup>(1)</sup>			500	μs

<sup>1.</sup> Current sense signal delay after positive input slope.

Table 9. V<sub>CC</sub> output diode

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
V <sub>F</sub>	Forward on voltage	- I <sub>OUT</sub> = 5.3A; T <sub>j</sub> = 150°C			0.6	V

Table 10. Protections<sup>(1)</sup>

Symbol	Parameter	Test conditions	Min.	Тур.	Max.	Unit
T <sub>TSD</sub>	Shutdown temperature		150	175	200	°C
T <sub>R</sub>	Reset temperature		135			°C
T <sub>hyst</sub>	Thermal hysteresis		7	15		°C
I <sub>lim</sub>	Current limitation	$V_{CC} = 13V$ 5V < $V_{CC}$ < 36V	30	45	75 75	A A
V <sub>demag</sub>	Turn-off output clamp voltage	$I_{OUT} = 2 A;$ $V_{IN} = 0V;$ L = 6mH	V <sub>CC</sub> - 41	V <sub>CC</sub> - 48	V <sub>CC</sub> - 55	٧
V <sub>ON</sub>	Output voltage drop limitation	I <sub>OUT</sub> = 1 A; T <sub>j</sub> = -40°C150°C		50		mV

To ensure long term reliability under heavy over-load or short circuit conditions, protection and related diagnostic signals must be used together with a proper software strategy. If the device operates under abnormal conditions this software must limit the duration and number of activation cycles.

Table 11. Truth table

Conditions	Input	Output	Sense
Normal operation	L	L	0
	H	H	Nominal
Over-temperature	L	L	0
	H	L	V <sub>SENSEH</sub>
Under-voltage	L H	L L	0
Over-voltage	L H	L L	0
Short circuit to GND	L	L	0
	H	L	(T <sub>j</sub> <t<sub>TSD) 0</t<sub>
	H	L	(T <sub>j</sub> >T <sub>TSD</sub> ) V <sub>SENSEH</sub>
Short circuit to V <sub>CC</sub>	L	H	0
	H	H	< Nominal
Negative output voltage clamp	L	L	0

Table 12. Electrical transient requirements

iable 121 Electrical transfer requirements						
ISO T/R	Test level					
7637/1 Test pulse	ı	II	III	IV	Delays and impedance	
1	- 25V <sup>(1)</sup>	- 50V <sup>(1)</sup>	- 75V <sup>(1)</sup>	- 100V <sup>(1)</sup>	2ms, 10Ω	
2	+ 25V <sup>(1)</sup>	+ 50V <sup>(1)</sup>	+ 75V <sup>(1)</sup>	+ 100V <sup>(1)</sup>	0.2ms, 10Ω	
3a	- 25V <sup>(1)</sup>	- 50V <sup>(1)</sup>	- 100V <sup>(1)</sup>	- 150V <sup>(1)</sup>	0.1μs, 50Ω	
3b	+ 25V <sup>(1)</sup>	+ 50V <sup>(1)</sup>	+ 75V <sup>(1)</sup>	+ 100V <sup>(1)</sup>	$0.1 \mu s$ , $50 \Omega$	
4	- 4V <sup>(1)</sup>	- 5V <sup>(1)</sup>	- 6V <sup>(1)</sup>	- 7V <sup>(1)</sup>	100ms, $0.01\Omega$	
5	+ 26.5V <sup>(1)</sup>	+ 46.5V <sup>(2)</sup>	+ 66.5V <sup>(2)</sup>	+ 86.5V <sup>(2)</sup>	400ms, $2\Omega$	

<sup>1.</sup> All functions of the device are performed as designed after exposure to disturbance.

<sup>2.</sup> One or more functions of the device is not performed as designed after exposure and cannot be returned to proper operation without replacing the device.

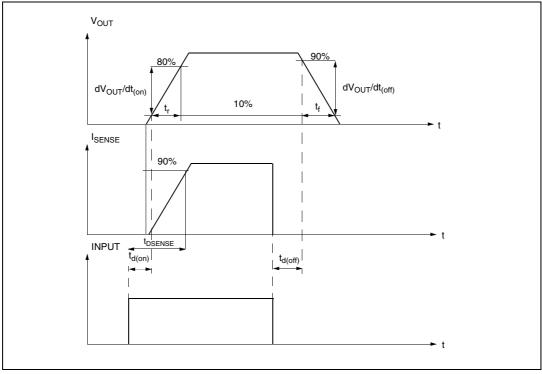
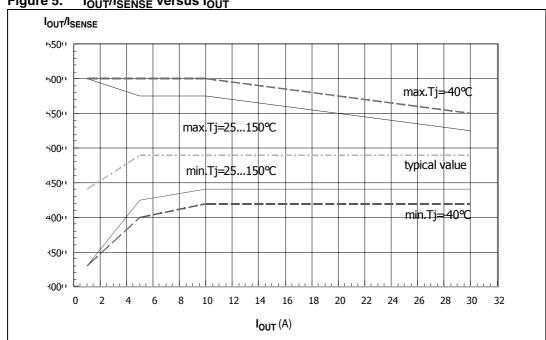


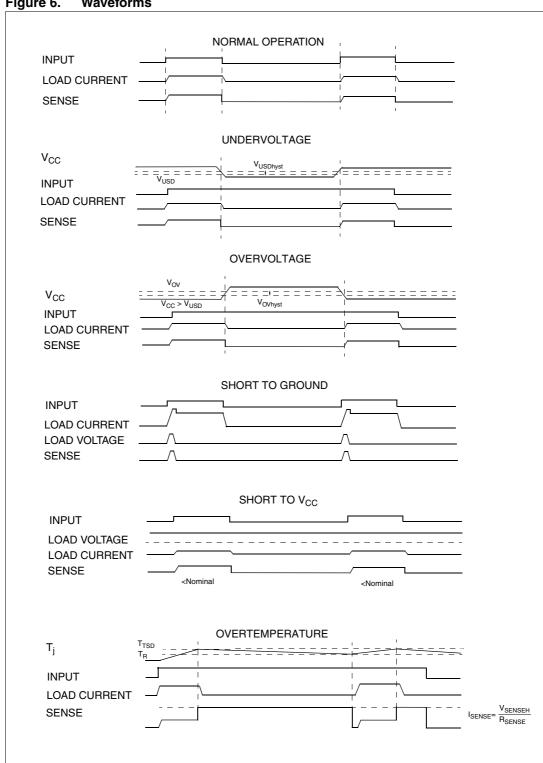
Figure 4. **Switching characteristics** 





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#### 2.4 Electrical characteristics curves

Figure 7. Off-state output current

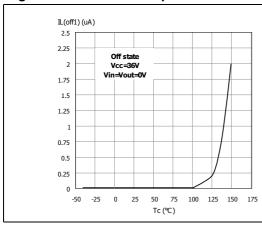


Figure 8. High-level input current

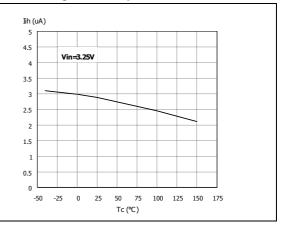


Figure 9. Input clamp voltage

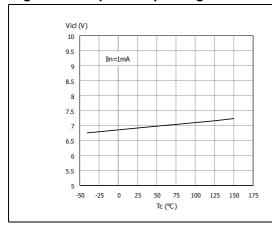


Figure 10. Turn-on voltage slope

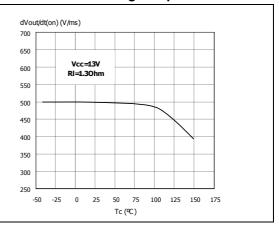


Figure 11. Over-voltage shutdown

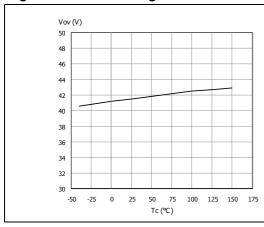


Figure 12. Turn-off voltage slope

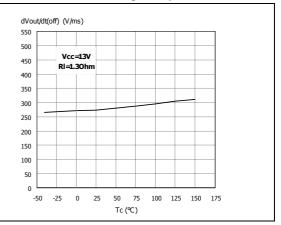


Figure 13.  $I_{LIM}$  vs  $T_{case}$ 

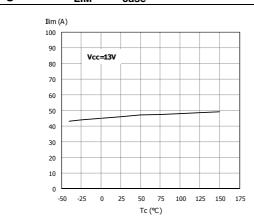


Figure 14. On-state resistance vs V<sub>CC</sub>

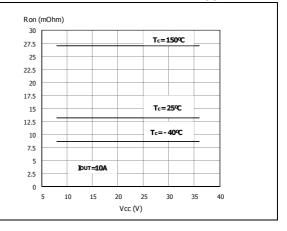


Figure 15. Input high-level

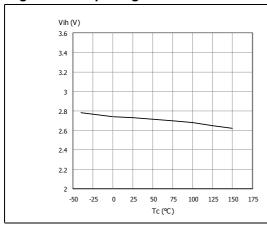


Figure 16. Input hysteresis voltage

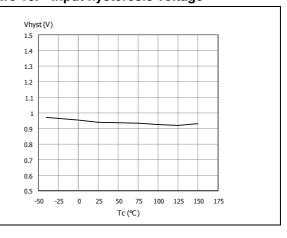


Figure 17. On-state resistance vs Tcase

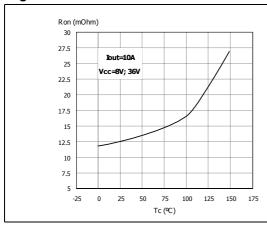
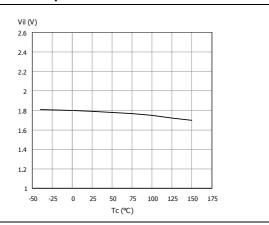
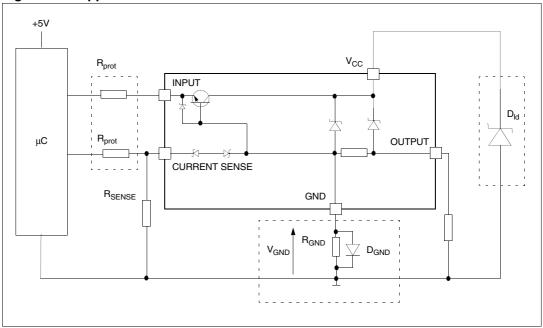


Figure 18. Input low-level



### 3 Application information

Figure 19. Application schematic



### 3.1 GND protection network against reverse battery

#### 3.1.1 Solution 1: resistor in the ground line (R<sub>GND</sub> only)

This can be used with any type of load.

The following is an indication on how to dimension the  $\ensuremath{\mathsf{R}_{\mathsf{GND}}}$  resistor.

- 1.  $R_{GND} \leq 600 \text{mV} / (I_{S(on)max})$ .
- 2.  $R_{GND} \ge (-V_{CC}) / (-I_{GND})$

where - I<sub>GND</sub> is the DC reverse ground pin current and can be found in the absolute maximum rating section of the device datasheet.

Power Dissipation in  $R_{GND}$  (when  $V_{CC} < 0$ : during reverse battery situations) is:

$$P_{D} = (-V_{CC})^2 / R_{GND}$$

This resistor can be shared amongst several different HSDs. Please note that the value of this resistor should be calculated with formula (1) where  $I_{S(on)max}$  becomes the sum of the maximum on-state currents of the different devices.

Please note that if the microprocessor ground is not shared by the device ground then the  $R_{GND}$  will produce a shift ( $I_{S(on)max} * R_{GND}$ ) in the input thresholds and the status output values. This shift will vary depending on how many devices are ON in the case of several high-side drivers sharing the same  $R_{GND}$ .

If the calculated power dissipation leads to a large resistor or several devices have to share the same resistor then ST suggests to utilize Solution 2 (see below).

#### 3.1.2 Solution 2: diode (D<sub>GND</sub>) in the ground line

A resistor ( $R_{GND}$  = 1k $\Omega$ ) should be inserted in parallel to  $D_{GND}$  if the device drives an inductive load.

This small signal diode can be safely shared amongst several different HSDs. Also in this case, the presence of the ground network will produce a shift ( $\approx 600 \text{mV}$ ) in the input threshold and in the status output values if the microprocessor ground is not common to the device ground. This shift will not vary if more than one HSD shares the same diode/resistor network.

Series resistor in INPUT and STATUS lines are also required to prevent that, during battery voltage transient, the current exceeds the absolute maximum rating.

Safest configuration for unused INPUT and STATUS pin is to leave them unconnected.

### 3.2 Load dump protection

 $D_{ld}$  is necessary (Voltage Transient Suppressor) if the load dump peak voltage exceeds the  $V_{CC}$  max DC rating. The same applies if the device is subject to transients on the  $V_{CC}$  line that are greater than the ones shown in the ISO 7637-2: 2004(E) table.

#### 3.3 MCU I/Os protection

If a ground protection network is used and negative transient are present on the  $V_{CC}$  line, the control pins will be pulled negative. ST suggests to insert a resistor ( $R_{prot}$ ) in line to prevent the  $\mu C$  I/Os pins to latch-up.

The value of these resistors is a compromise between the leakage current of  $\mu C$  and the current required by the HSD I/Os (Input levels compatibility) with the latch-up limit of  $\mu C$  I/Os.

-V<sub>CCpeak</sub>/I<sub>latchup</sub> ≤R<sub>prot</sub> ≤(V<sub>OHµC</sub>-V<sub>IH</sub>-V<sub>GND</sub>) / I<sub>IHmax</sub>

Calculation example:

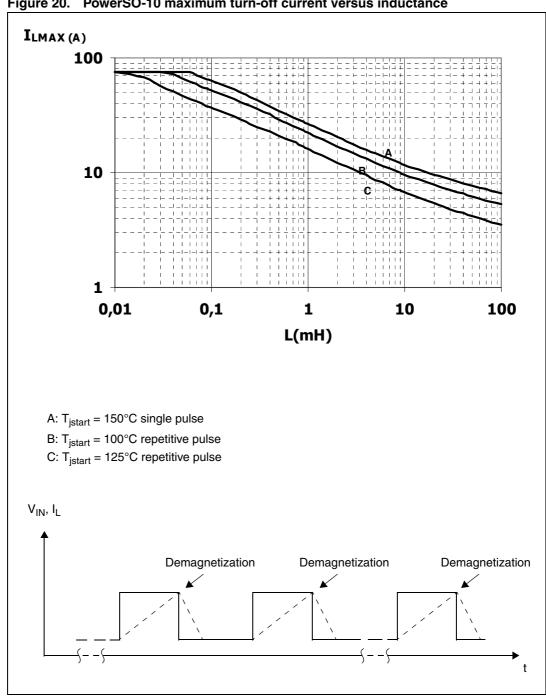
For  $V_{CCpeak}$ = - 100V and  $I_{latchup} \ge 20mA$ ;  $V_{OH\mu C} \ge 4.5V$ 

 $5k\Omega \le R_{prot} \le 65k\Omega$ 

Recommended values:  $R_{prot} = 10k\Omega$ .

#### 3.4 PowerSO-10 maximum demagnetization energy ( $V_{CC} = 13.5V$ )

Figure 20. PowerSO-10 maximum turn-off current versus inductance



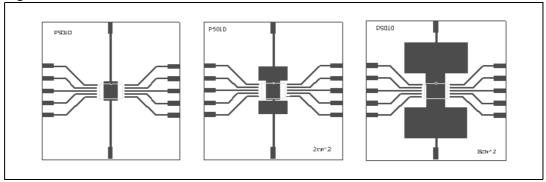
Note:

Values are generated with  $R_L = 0 \Omega$  In case of repetitive pulses,  $T_{jstart}$  (at beginning of each demagnetization) of every pulse must not exceed the temperature specified above for curves A and B.

### 4 Package and PCB thermal data

#### 4.1 PowerSO-10 thermal data

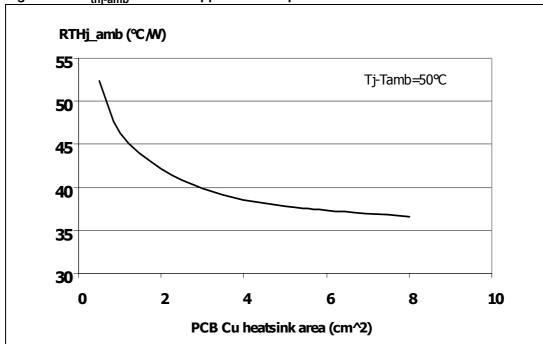
Figure 21. PowerSO-10 PC board



Note:

Layout condition of  $R_{th}$  and  $Z_{th}$  measurements (PCB FR4 area = 58mm x 58mm, PCB thickness = 2mm, Cu thickness = 35 $\mu$ m, Copper areas: from minimum pad lay-out to 8cm<sup>2</sup>).

Figure 22. R<sub>thj-amb</sub> Vs PCB copper area in open box free air condition



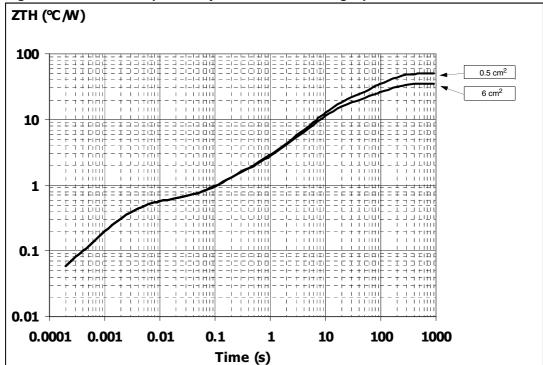
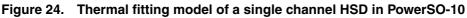


Figure 23. Thermal impedance junction ambient single pulse

Equation 1: pulse calculation formula

$$\begin{split} Z_{TH\delta} &= \, R_{TH} \cdot \, \, \delta + Z_{THtp} (1 - \delta) \\ \text{where} \quad \delta &= \, t_p / \, \, T \end{split}$$



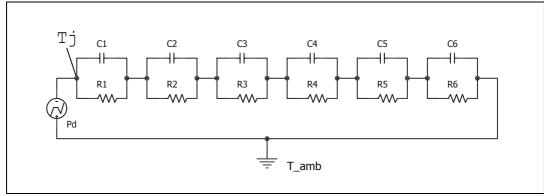


Table 13. Thermal parameters

Area / island (cm <sup>2</sup> )	Footprint	6
R1 (°C/W)	0.02	
R2 (°C/W)	0.1	
R3 (°C/W)	0.2	
R4 (°C/W)	0.8	
R5 (°C/W)	12	
R6 (°C/W)	37	22
C1 (W.s/°C)	0.0015	
C2 (W.s/°C)	7E-03	
C3 (W.s/°C)	0.015	
C4 (W.s/°C)	0.3	
C5 (W.s/°C)	0.75	
C6 (W.s/°C)	3	5

### 5 Package and packing information

## 5.1 ECOPACK® packages

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com. ECOPACK® is an ST trademark.

#### 5.2 PowerSO-10 mechanical data

Table 14. PowerSO-10 mechanical data

Dim		mm	
Dim.	Min.	Тур.	Max.
А	3.35		3.65
A <sup>(1)</sup>	3.4		3.6
A1	0		0.10
В	0.40		0.60
B <sup>(1)</sup>	0.37		0.53
С	0.35		0.55
C <sup>(1)</sup>	0.23		0.32
D	9.40		9.60
D1	7.40		7.60
E	9.30		9.50
E2	7.20		7.60
E2 <sup>(1)</sup>	7.30		7.50
E4	5.90		6.10
E4 <sup>(1)</sup>	5.90		6.30
е		1.27	
F	1.25		1.35
F <sup>(1)</sup>	1.20		1.40
Н	13.80		14.40
H <sup>(1)</sup>	13.85		14.35
h		0.50	
L	1.20		1.80
L <sup>(1)</sup>	0.80		1.10
α	0°		8°
α <sup>(1)</sup>	2°		8°

<sup>1.</sup> Muar only POA P013P.

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#### 5.3 PowerSO-10 packing information

Figure 26. PowerSO-10 suggested Figure 27. PowerSO-10 tube shipment (no suffix) pad layout

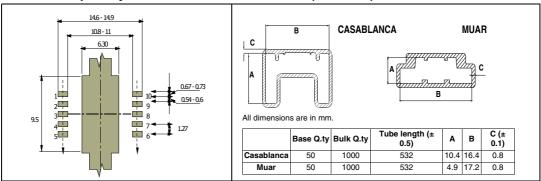
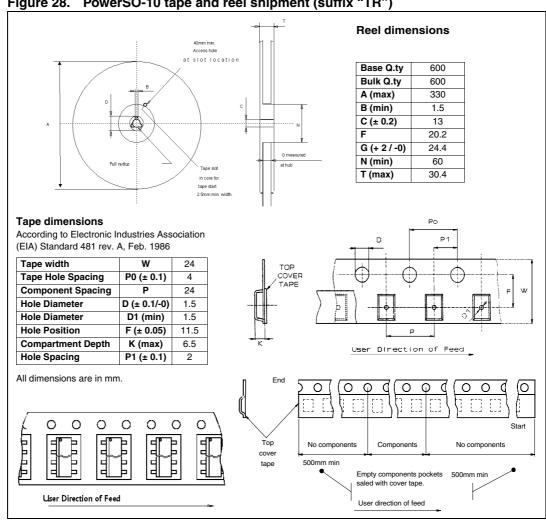


Figure 28. PowerSO-10 tape and reel shipment (suffix "TR")



VN920SP Revision history

# 6 Revision history

Table 15. Document revision history

Date	Revision	Changes
14-Jul-2004	1	Initial release.
03-May-2006	2	Minor changes. Current and voltage convention update (page 2). Configuration diagram (top view) and suggested connections for unused and n.c. pins insertion (page 2). 6 cm2 Cu condition insertion in thermal data table (page 3). V <sub>CC</sub> - output diode section update (page 4). Revision history table insertion (page 34). Disclaimers update (page 35).
17-Dec-2008	3	Document reformatted and restructured.  Added content, list of figures and tables.  Added <i>ECOPACK® packages</i> information.

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